

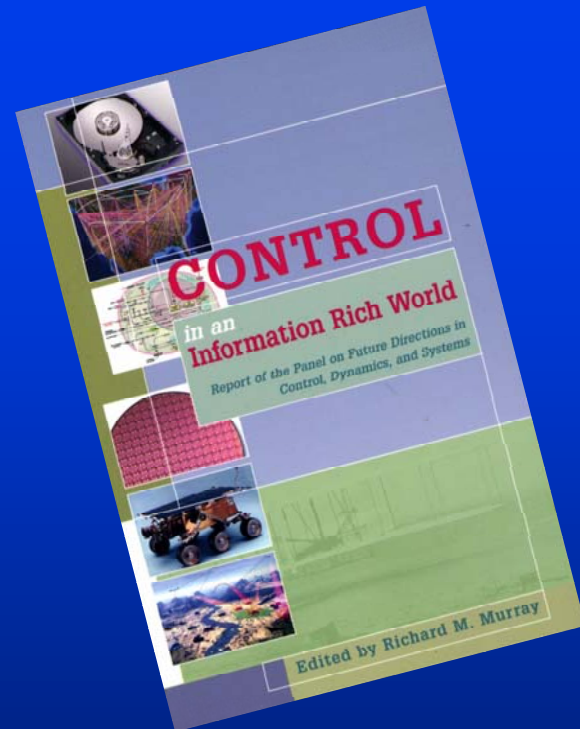
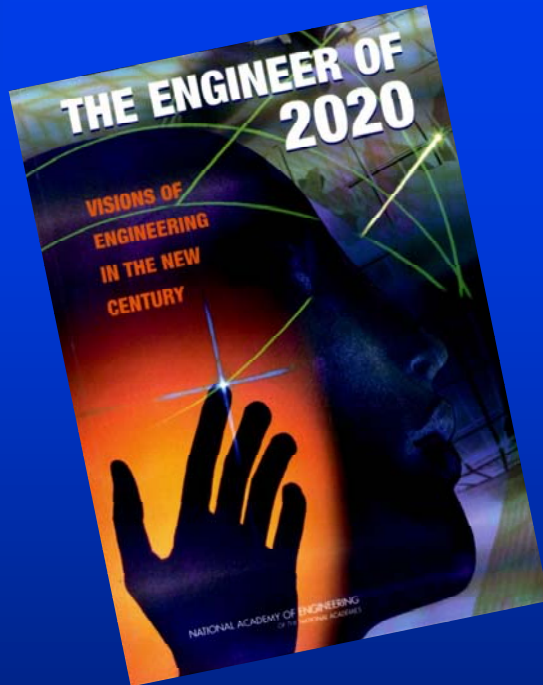


Present Developments in Control Applications

K. J. Åström

Lund University
Sweden

Acknowledgements



Numerous friends and colleagues in industry and academia

Control Emerges

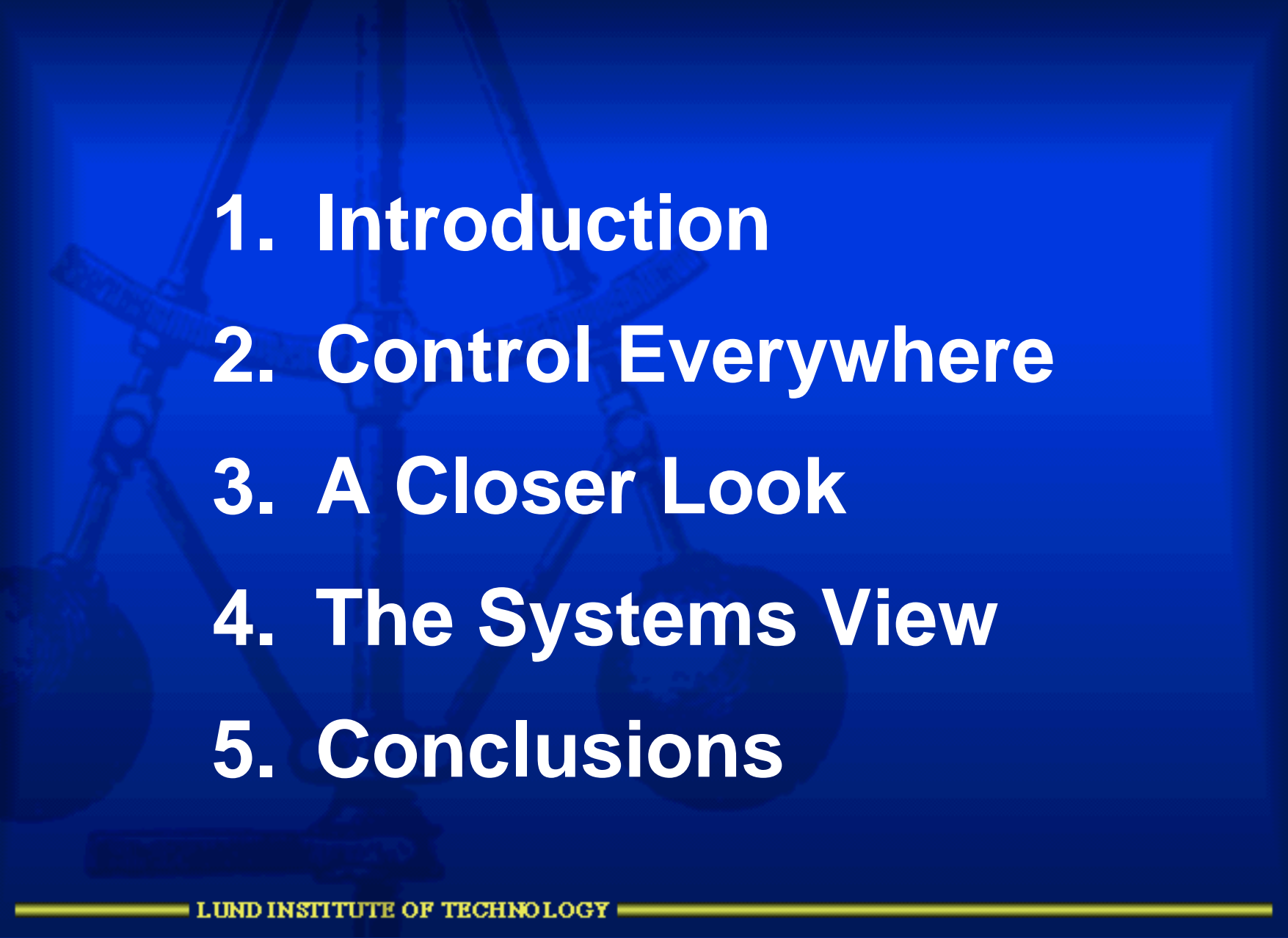
- Drivers: gun control, radar ...
- Block diagrams, transfer functions
- Design tools: graphical
- Analog computing
- Holistic view of theory & applications

The Second Phase

- Drivers: space, computer control, mathematics
- Rapid growth of subspecialities
- Optimal, stochastic, nonlinear, ...
- Computational tools
- Impressive development of theory
- Holistic view was lost

The Third Phase?

- Drivers: embedded systems, networks, biology, physics, ...
- Autonomy, distribution
- Exploding applications
- Hardware and software platforms
- Holistic view will be recovered?

- 
- 1. Introduction**
 - 2. Control Everywhere**
 - 3. A Closer Look**
 - 4. The Systems View**
 - 5. Conclusions**

Breakthrough Technologies

Everything will, in some sense, be smart; that is, every product, every service, and every bit of infrastructure will be attuned to the needs of the humans it serves and will adapt its behavior to those needs.

Sensing, actuation, and control

NAE The Engineer of 2020

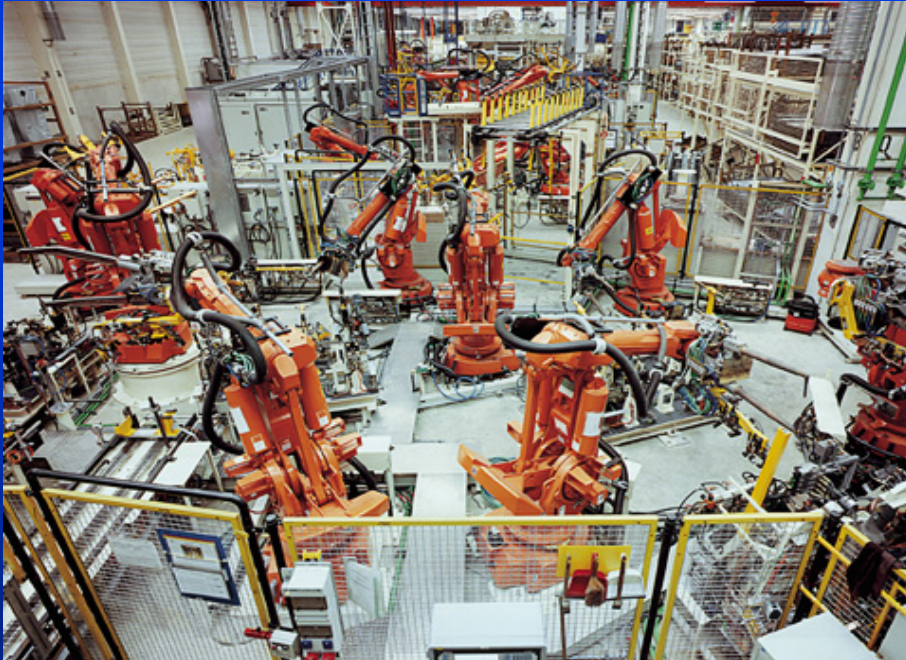
Power Generation and Distribution



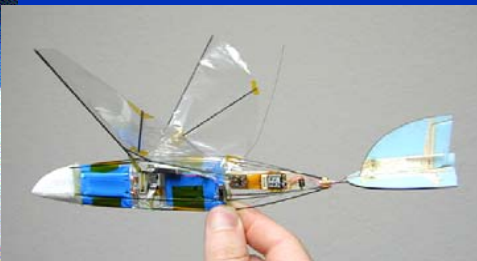
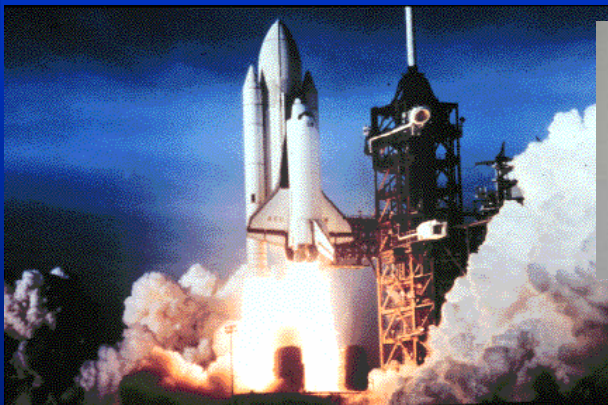
Process Control



Discrete Manufacturing



Vehicles



Consumer Electronics



Biomedical

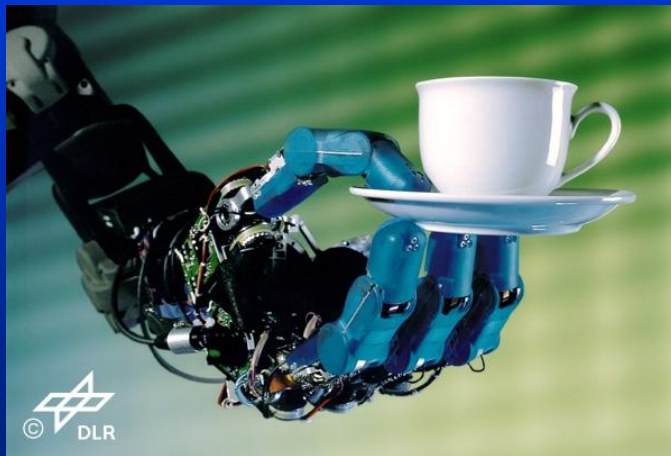


DLR Robots and Hands

LWR III: 7 joints weight/load ~ 1

150 W, 3 cables

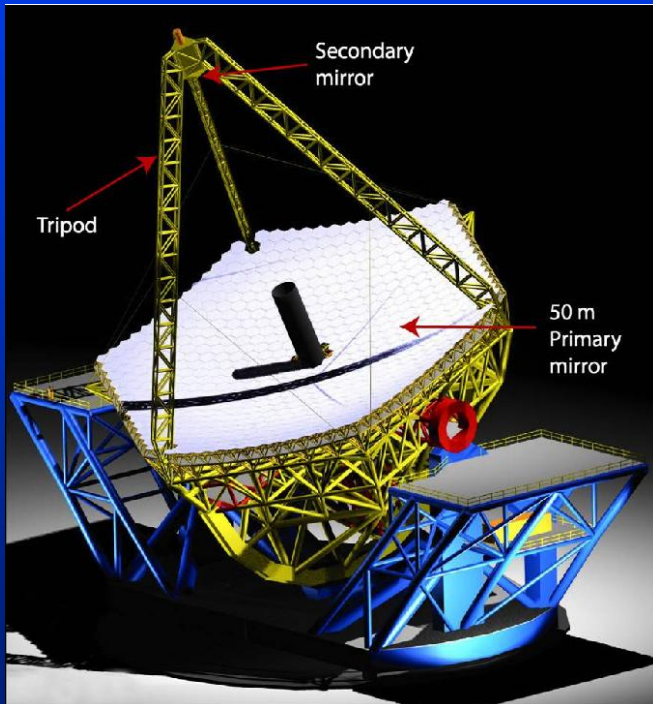
Hand II: 13 joints 3 kg finger force



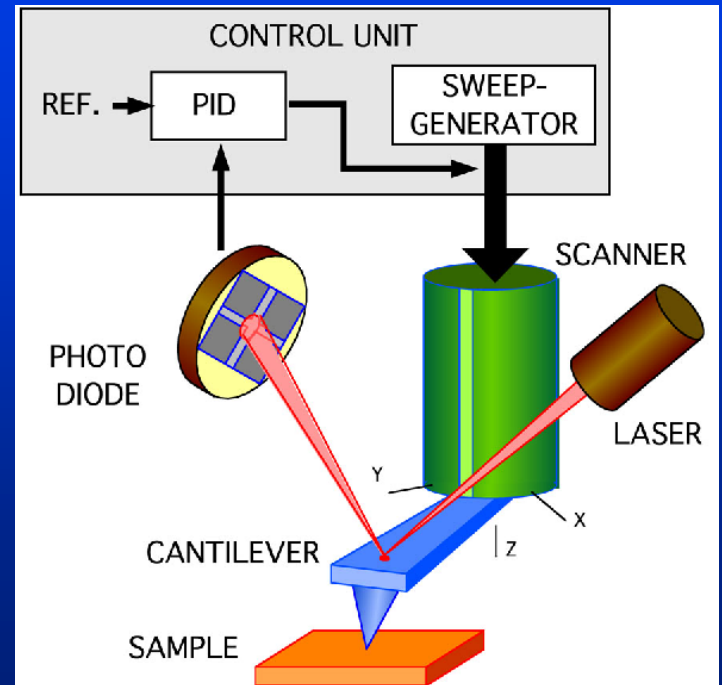
Gerd Hirzinger DLR

Instruments Giga to Nano

Adaptive Optics



Atomic Force Microscope



Physics

- ◆ Devices and ideas (feedback in nature)
- ◆ Particle Accelerators
- ◆ Adaptive Optics
- ◆ Atomic Force Microscope
- ◆ Quantum and Molecular Systems
 - NMR, Quantum computing
- ◆ Turbulence

Biology

Feedback is a central feature of life. The process of feedback governs how we grow, respond to stress and challenge, and regulate factors such as body temperature, blood pressure, and cholesterol level.

The mechanisms operate at every level, from the interaction of proteins in cells to the interaction of organisms in complex ecologies.

Key Drivers

- **Insight and understanding**
- **Knowledge and education**
- **Power of feedback and computing**
- **Tools**
- **Control a commodity?**

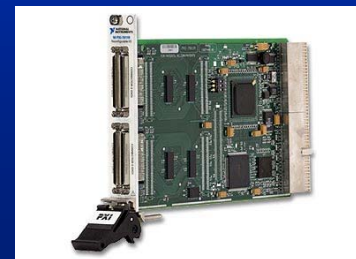
The Power of Feedback

- Good systems from bad components
- Attenuate disturbances
- Stabilize unstable system
- Shape behavior
- Risk of instability

Tools



- Sensors, actuators, process interfaces
- Computers, signal processors, FPGA
- Tools for modeling, analysis, simulation and design
- Operating systems, automatic code generation



NASA's X43-A Scramjet Achieves Record-Breaking Mach 10 Speed Using MathWorks Tools for Model-Based Design

The Challenge

To design and automatically generate flight control software for a scramjet vehicle traveling at Mach 10 speed

The Solution

Use Simulink® to model and validate control systems, Real-Time Workshop® to automatically generate flight code, and MATLAB® to process and analyze post-flight data

The Results

Reduced development time by months
Accurately predicted separation clearance
Aided in achieving SEI CMM Level 5 process rating



The X43-A on its record-setting flight.

Our autopilot worked on the first try, which is amazing given that a vehicle like this had never been flown before. MathWorks tools helped us design and implement control systems that kept the vehicle stable throughout the flight."

*Dave Bose,
Analytical Mechanics Associates*

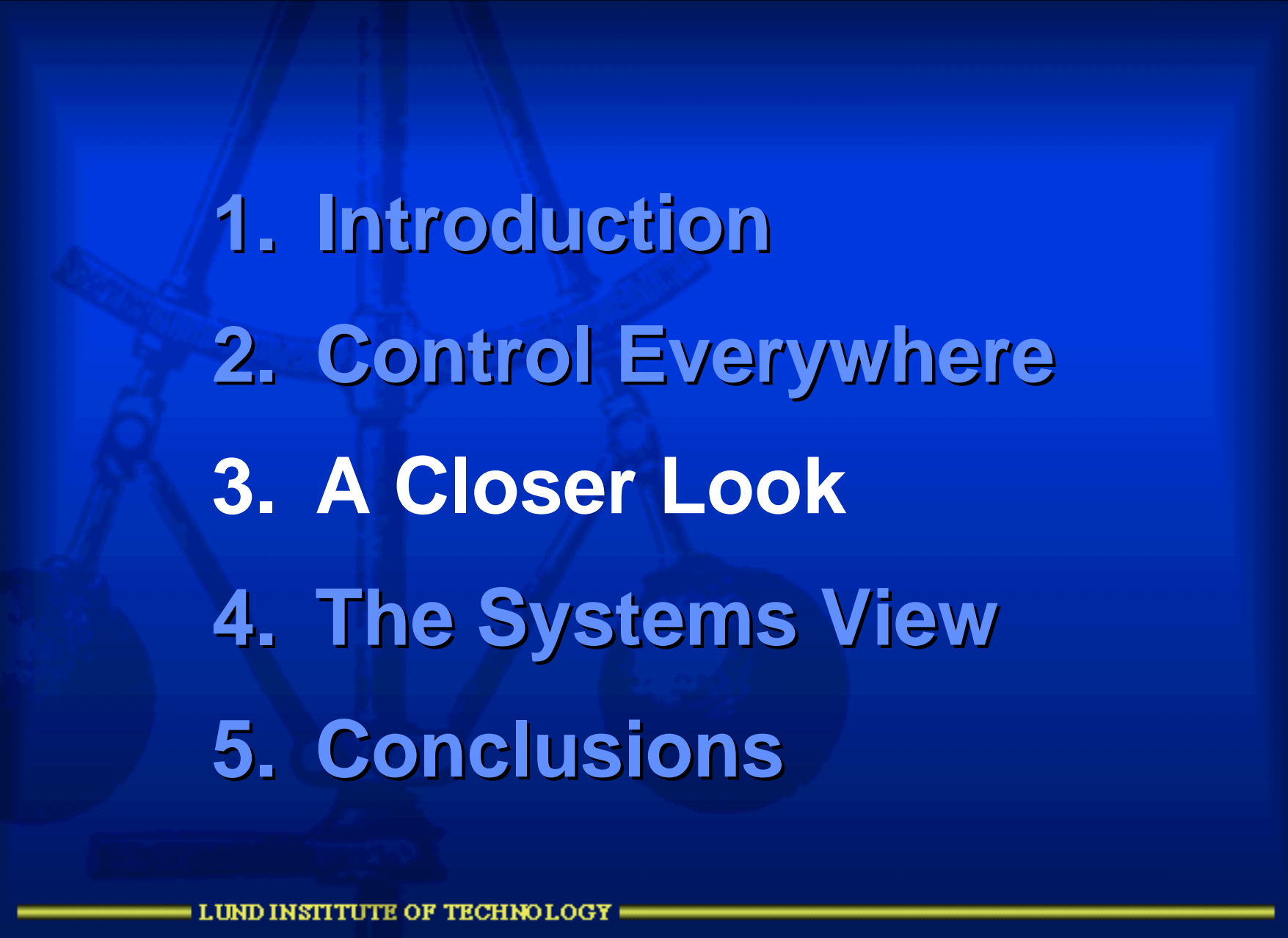
Rapid Prototyping

NI CompactRIO

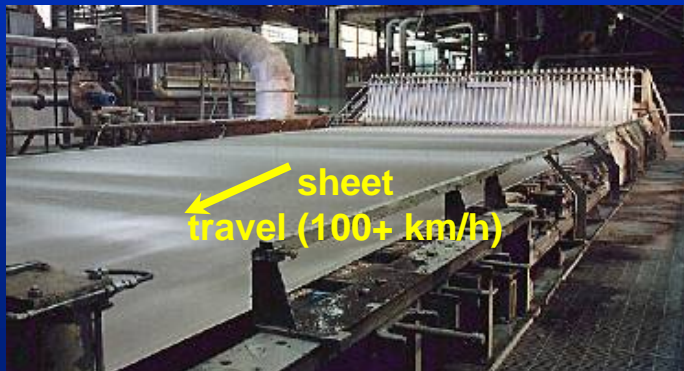
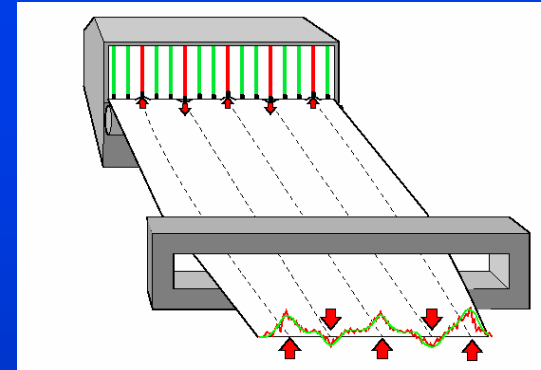
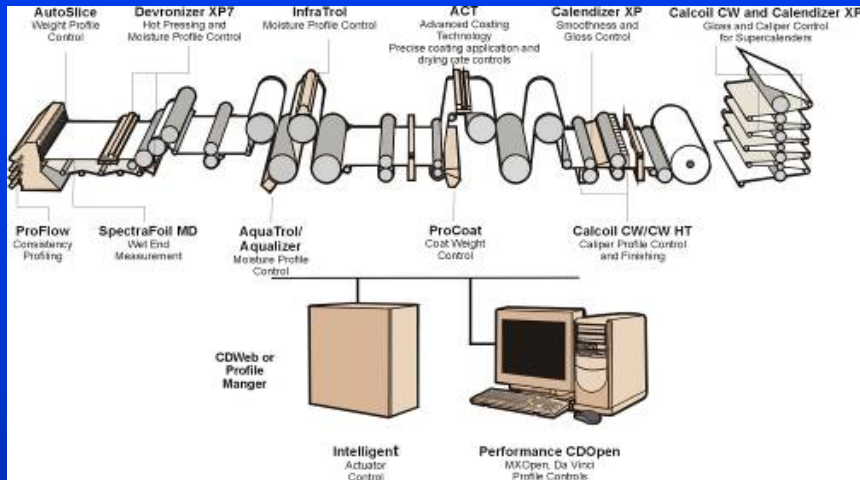


Drivven: "We prototyped a full-authority engine control system ... in just 3 man-months. In past projects, it took us at least 2 man-years and over \$500,000 to develop similar ECU systems."



- 
- 1. Introduction**
 - 2. Control Everywhere**
 - 3. A Closer Look**
 - 4. The Systems View**
 - 5. Conclusions**

Cross Direction Control



Several hundred sensors and actuators, millisecond operation, controlling paper thickness to within microns!

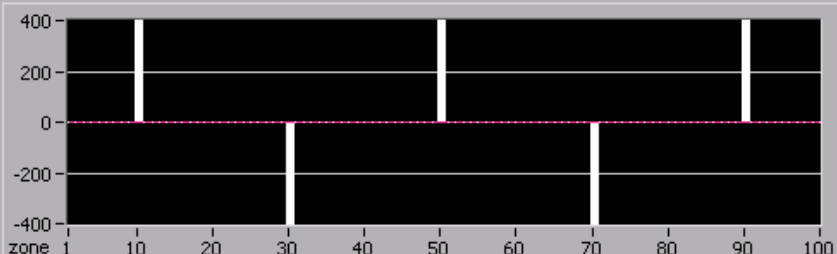
Honeywell Laboratories

PROCESS IDENTIFICATION

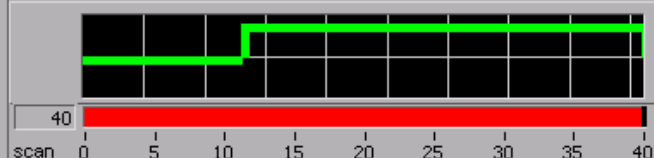
AutoSlice-CDW

Automatic ID OFF

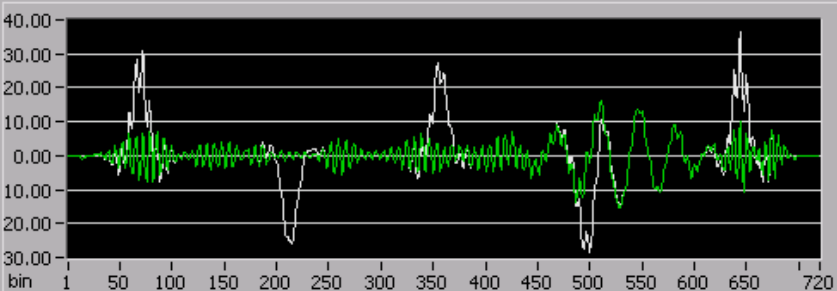
CD Bump Test Excitation Profile



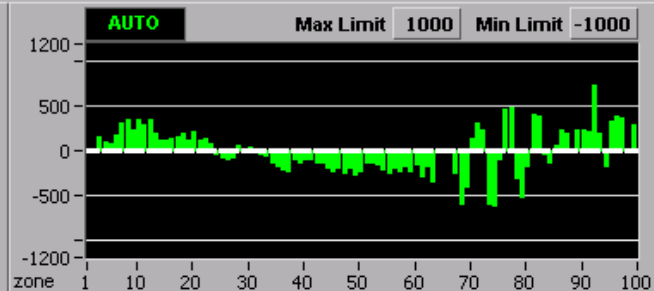
MD Bump Test Excitation Pattern



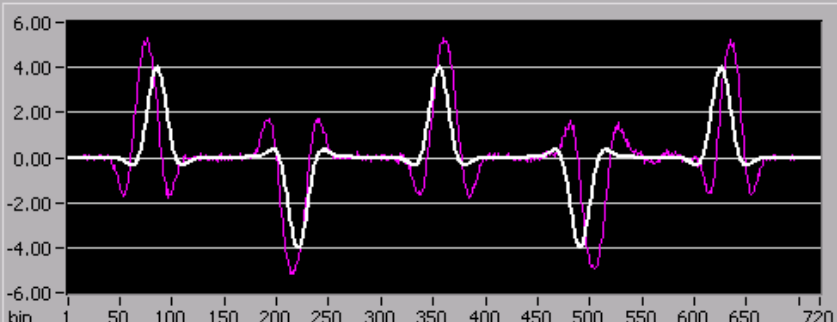
Current and Predicted High Resolution Profile



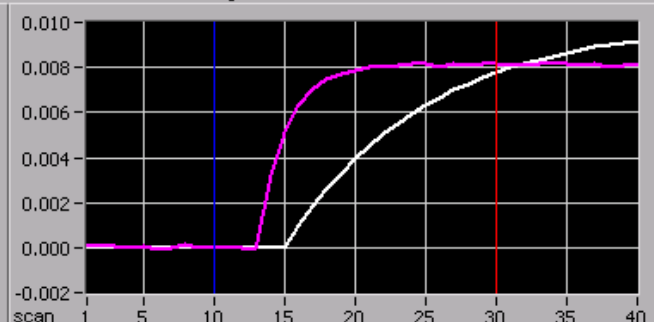
Actuator Setpoints Profile



CD Model Identification



Dynamic Model Identification



Low Sheet Edge	1.50	Shrinkage	6.30	High Sheet Edge	719.50
Low Actuator Offset	-321.36	Confidence	0.58	High Actuator Offset	-322.21

Controller Gain	0.01775	Time Constant	47.06
Time Delay	20.01	Average Scan Time	10.00

License Info...

Current Grade

My Grade

Scanner 1 Status

ODX Link Status

NO CONNECTION

Bump Test
ConfigurationProcess
IdentificationAlignment
ImplementationCD Control
TuningTuning
Implementation

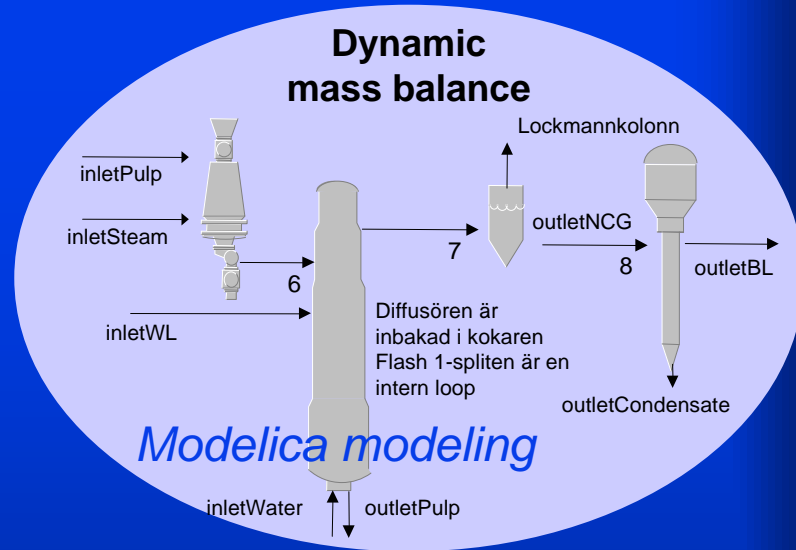
Reports

Color
TopographyStart
ODXLinkStop
ODXLink

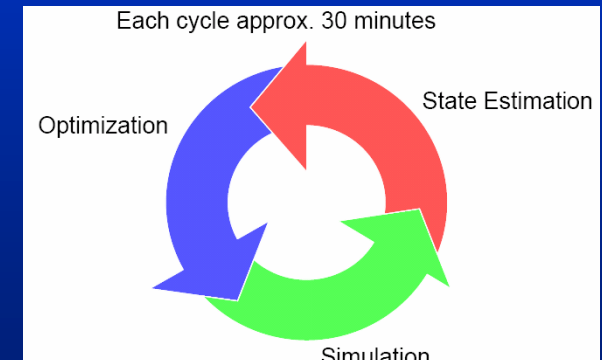
Print Screen

Minimize
IntelliMapExit
IntelliMapStart
Bump TestSave/Load
Bump Test DataIdentify
Overall ModelSpatial Model
IdentificationDynamic Model
IdentificationShrinkage Model
IdentificationSpatial Control
Fine TuningDynamic Control
Fine Tuning

Mill Wide Control



25	Production units
38	Buffer tanks
250	Streams
250	Measurements
2500	Variables



Slide from Alf Isaksson



Global Enterprise Control



Strategic, Enterprise system, global, 1-10 years

Tactical, Manufacturing system, 10 km, year, shift,

Operational, Process Control, 1 km, shift, ms

Embedded APC Tools – What's new?

- ***NO*** extra databases
- ***NO*** database synchronization issues
- ***NO*** watchdog timers
- ***NO*** fail/shed logic design
- ***NO*** custom DCS programming
- ***NO*** interface programming
- ***NO*** operator interface development



Traditional Advanced Control

Embedded APC:

- *Can run in DCS controllers*
- *Redundant and fast (1/sec)*
- *Integrated operator user interface*
- *Configuration through standard Control Studio*
- *Automated step and Model ID*
- *Off-line simulation and training*

Automotive

Engine control

Power trains

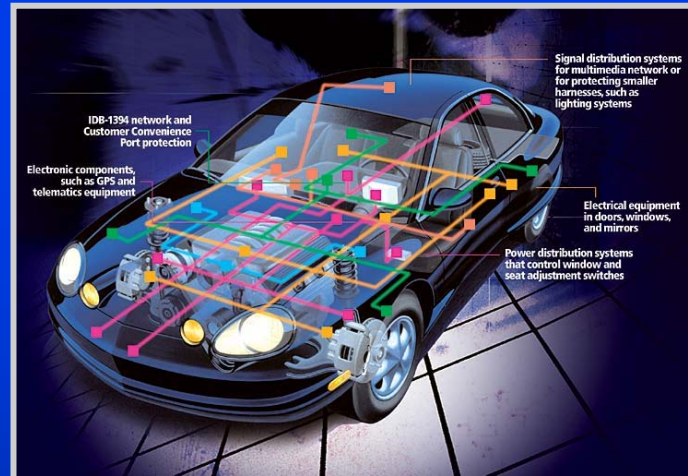
Cruise control

Adaptive cruise control

Traction control

Lane guidance assistance

Platooning

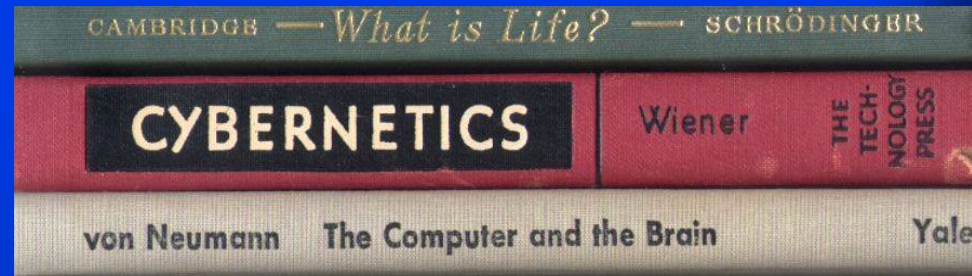


Automotive

- **Strongly enhanced performance**
- **Strong technology driver**
- **Large numbers (microcontroller)**
- **Low cost**
- **Safe design and operation of
networked embedded systems**

Biology

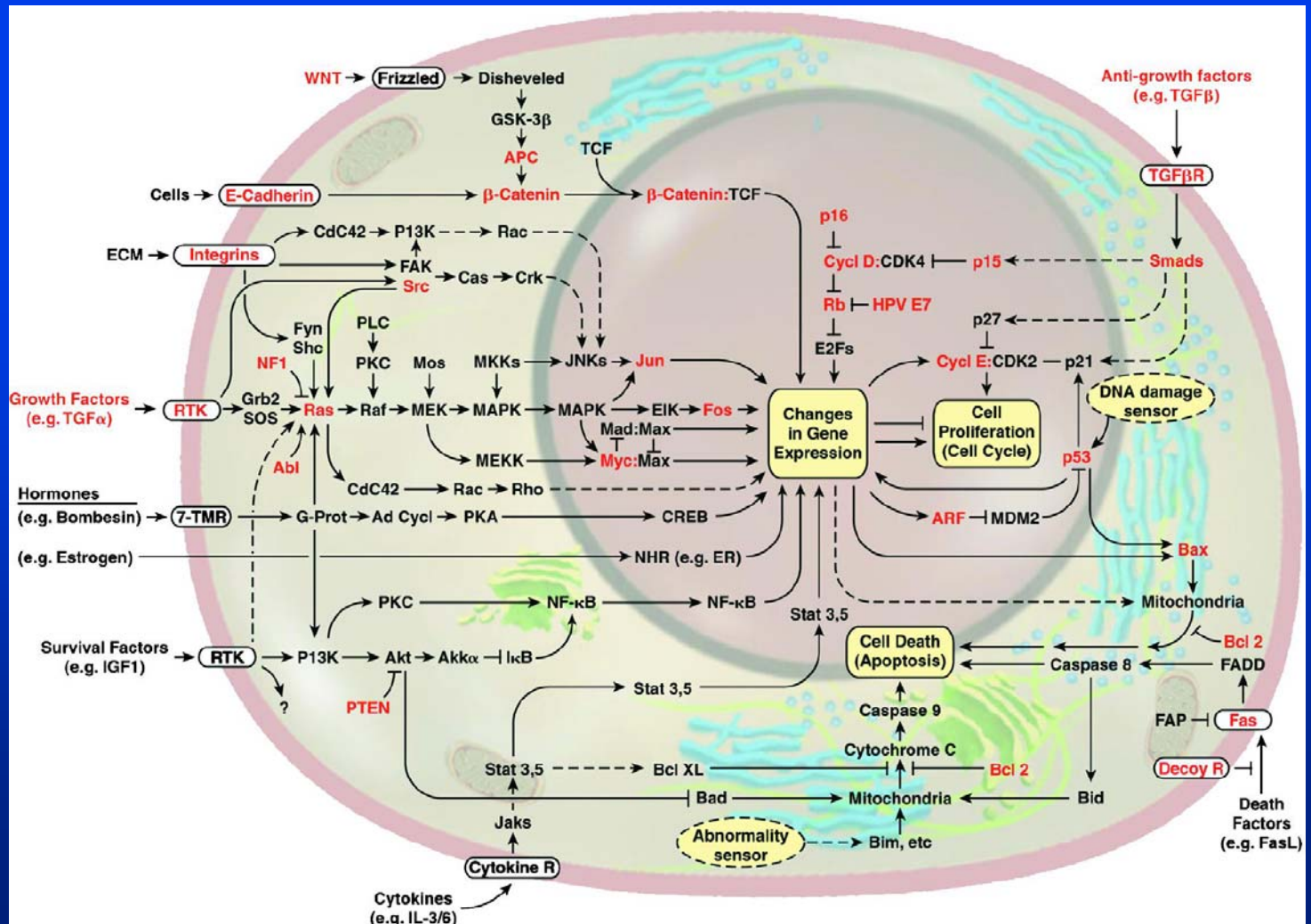
- **Schrödinger 1944**
- **Wiener 1948**
- **von Neumann 1958**
- **Bellman Mathematical Biosciences**
- **Understanding dynamics and control crucial**
- **Biomedical engineering**
- **Systems Biology**

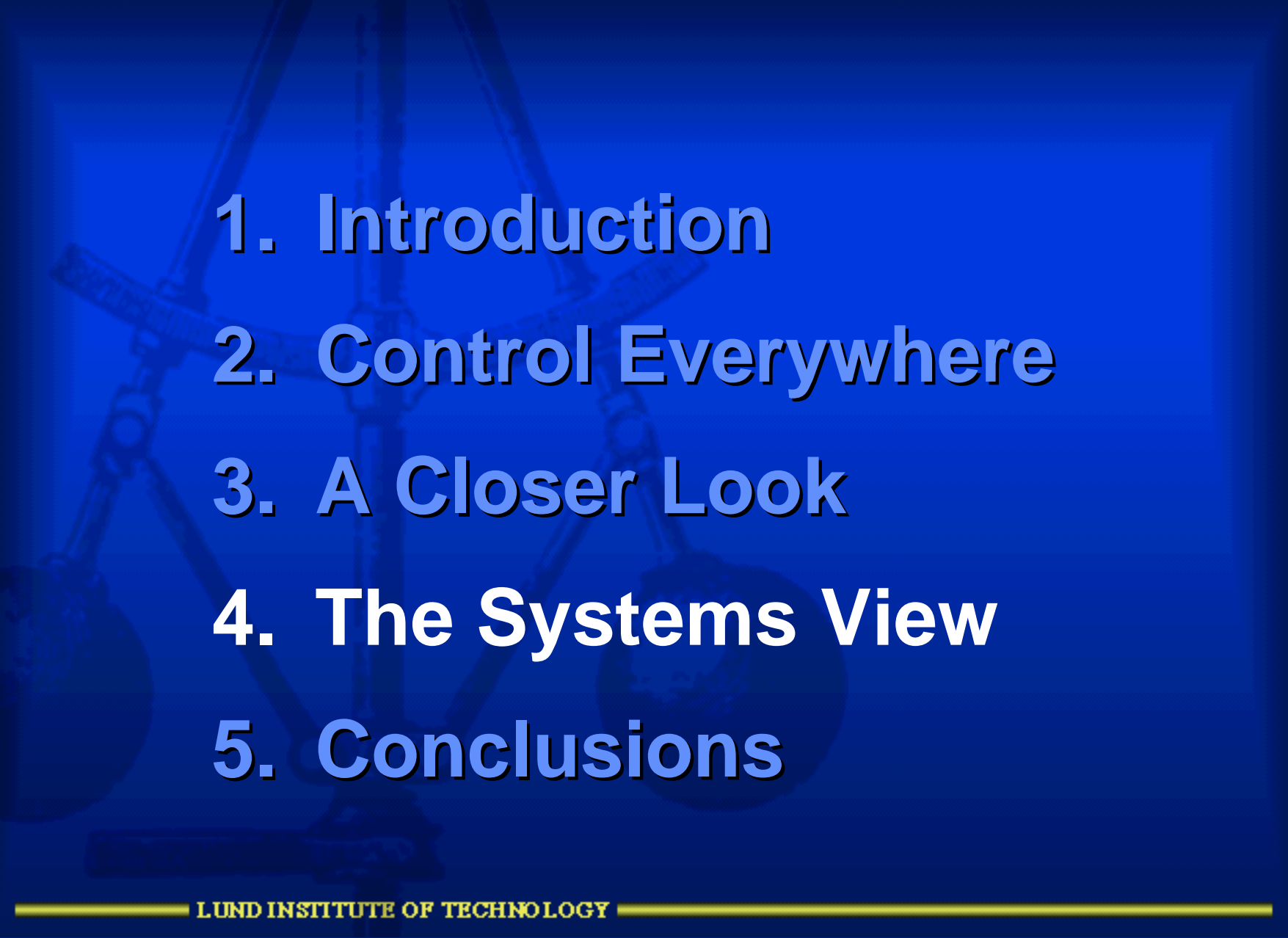


Systems Biology

Leading biologists have recognized that new systems-level knowledge is urgently required in order to conceptualize and organize the revolutionary developments taking place in the biological sciences, and new academic departments and educational programs are being established at major universities, particularly in Europe and in the United States

Signaling Circuit in Mammalian Cell



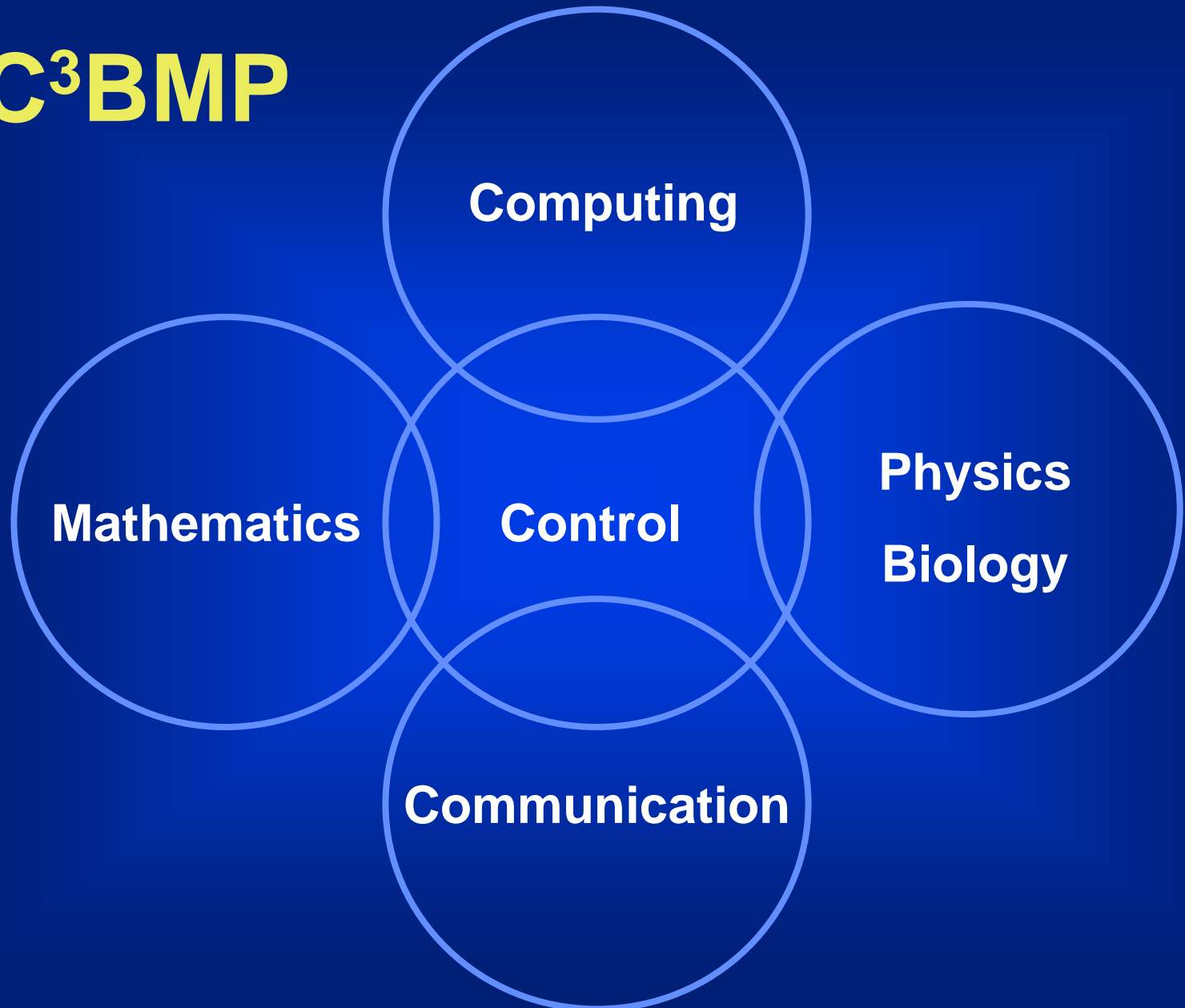
- 
1. Introduction
 2. Control Everywhere
 3. A Closer Look
 4. The Systems View
 5. Conclusions

The Systems Perspective

In the past steady increases in knowledge has spawned new microdisciplines within engineering. However, contemporary challenges

- from biomedical devices to complex manufacturing designs to large systems of networked devices
- increasingly require a systems perspective

C³BMP

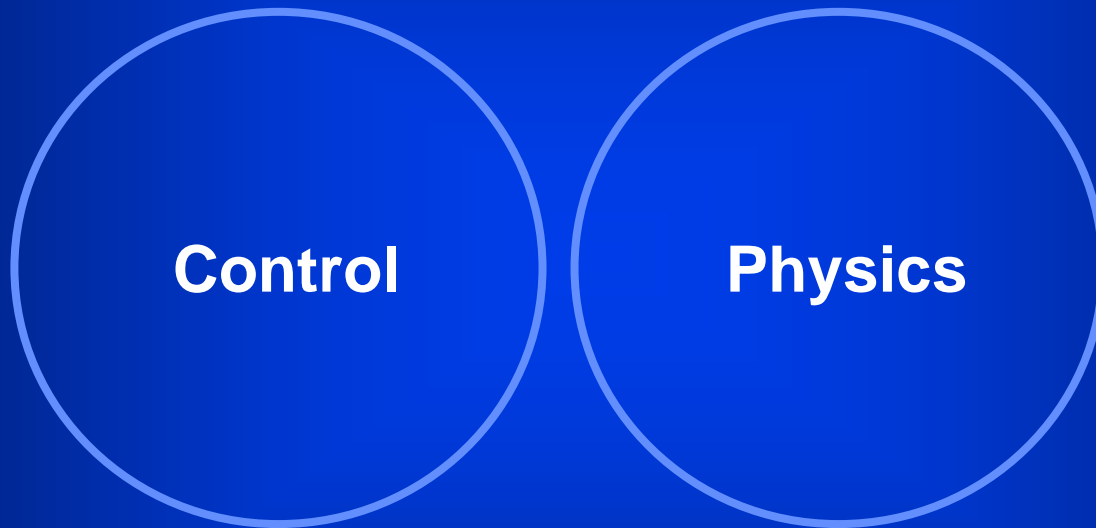


Modeling and Simulation

There will be growth in areas of simulation and modeling around the creation of new engineering “structures”. Computer-based design-build engineering ... will become the norm for most product designs, accelerating the creation of complex structures for which multiple subsystems combine to form a final product.

NAE The Engineer of 2020

The Modeling Barrier



Block diagrams ODEs

Mass, energy, momentum

Important to have multiple views

Block diagrams are not suitable for serious physical modeling

Modelica (www.modelica.org)

- Block diagrams and ODEs (imperative models) are not suited for physical modeling
- Behavior-based (declarative) modeling is a good alternative
- European activity based on industry/university collaboration
- Groups with broad competence and experience

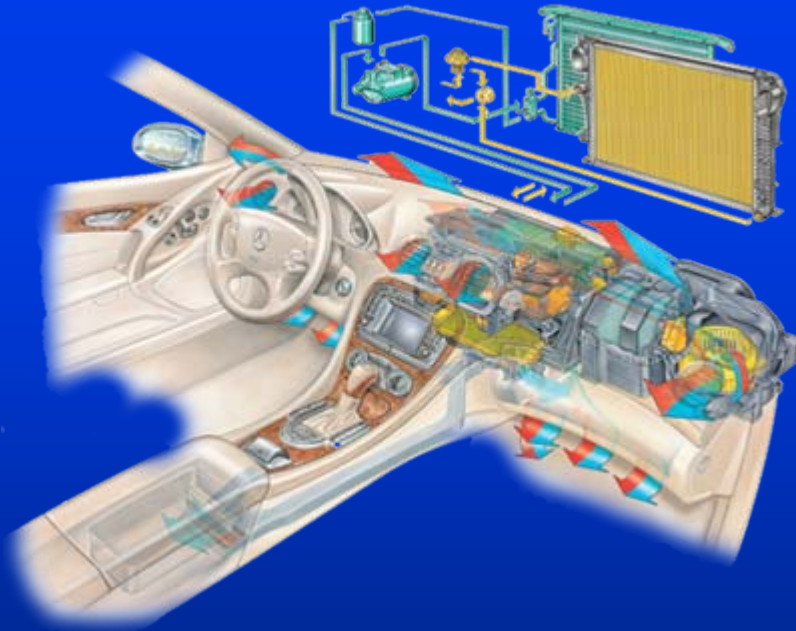


Modelica (www.modelica.org)

- Mimics how an engineer builds a real system
- Object oriented, component-based, multi-domain
- Efficient engineering through reuse
- Model libraries (free and commercial)
- Simulator Dymola
- Extensive symbolic manipulation, automatic inversion, ...
- Efficient real-time code
- Syntax and semantics formally defined



Automotive Climate Control



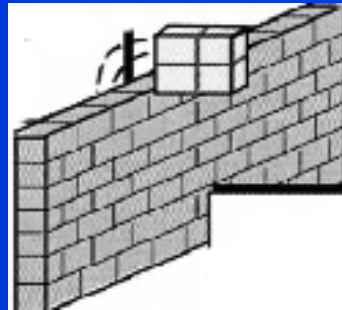
- Audi, BMW, DaimlerCrysler, Volkswagen and their suppliers have standardized on Modelica
- Suppliers provide components and validated Modelica models based on the AirConditioning library from Modelon
- Car manufacturers evaluate complete system by simulation
- IP protected by extensive encryption

Picture courtesy of Behr GmbH & Co.



The Implementation Barrier

Control



Computing

*Feedback, Stability,
Moderate complexity ODE, PDE
Robustness*

*Logic, languages, architecture
High complexity, DES, FSM
Abstractions*

Networked embedded systems

Control and Computing

Vannevar Bush 1927: Engineering can progress no faster than the mathematical analysis on which it is based. Formal mathematics is frequently inadequate for numerous problems, a mechanical solution offers the most promise.

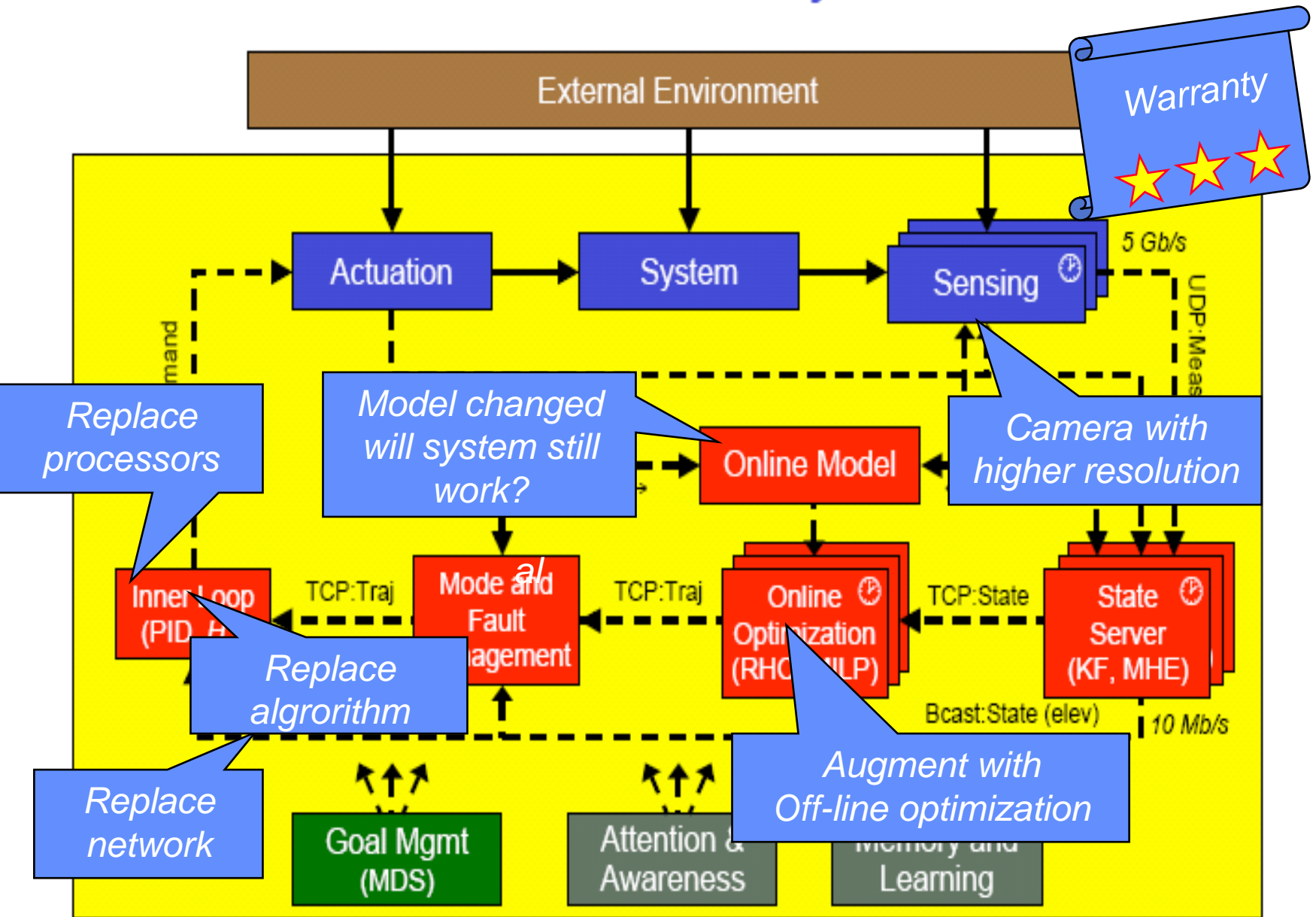
Herman Goldstine 1962: When things change by two orders of magnitude it is revolution not evolution.

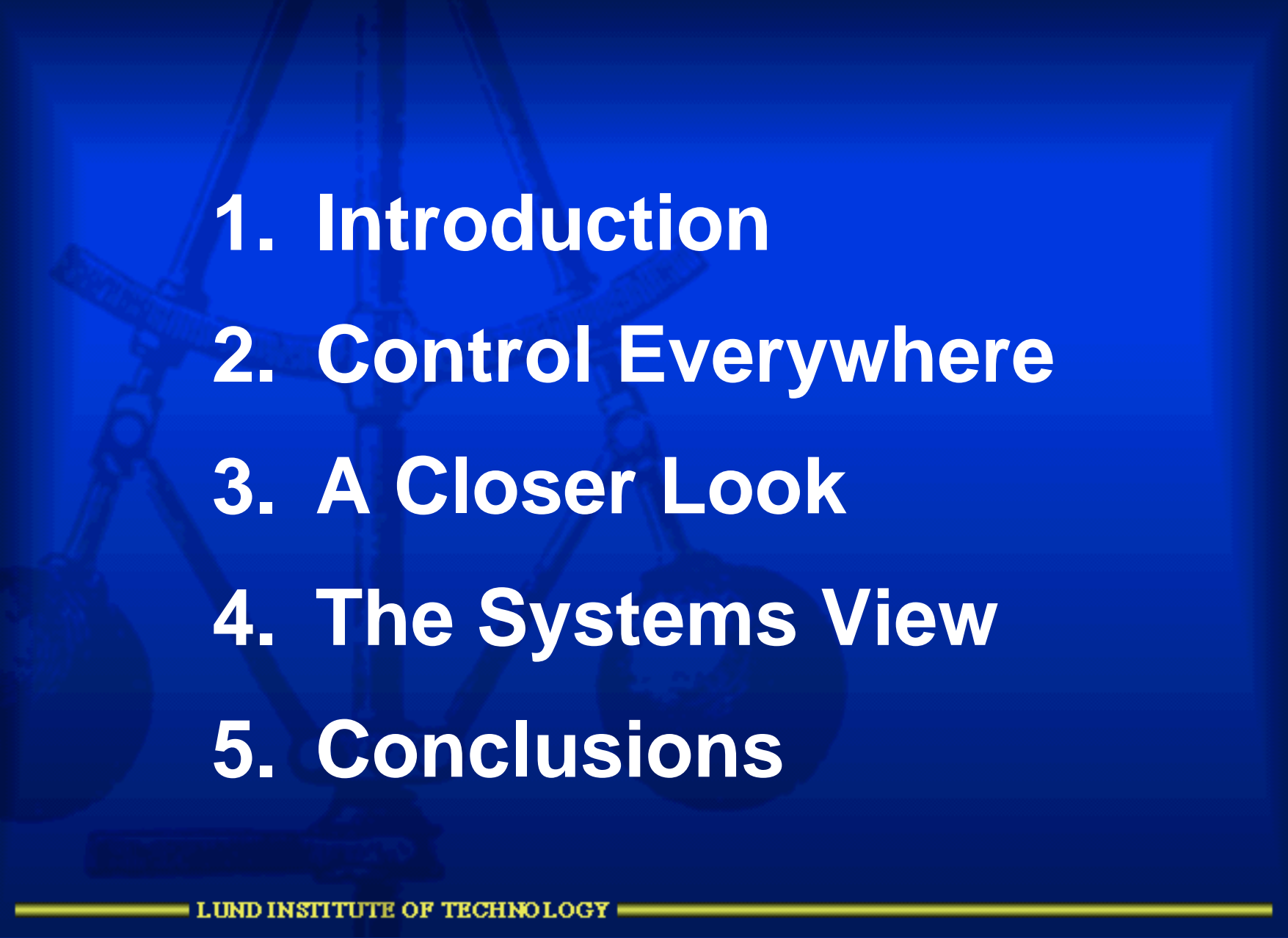
Gordon Moore 1965: The number of transistors per square inch on integrated circuits has doubled in approximately 18 months.

Software has unfortunately not kept up

Networked Embedded Systems

- It has been predicted that by the year 2010 about 90% of all program code will be implemented for embedded systems.
- Dramatic growth of complexity. Ex. automotive system: Thousands of functions, 10M lines of code, 5 bus systems, 80 ECUs
- How to design, commission, operate, and upgrade with guaranteed performance



- 
- 1. Introduction**
 - 2. Control Everywhere**
 - 3. A Closer Look**
 - 4. The Systems View**
 - 5. Conclusions**

Conclusions

- Tremendous advances
- Control everywhere
- Massive computations
- The systems challenge
- Like 1956 but at a higher level
- A role for IFAC?

