

Welcome to the course *System Identification (FRT 041)* at the Department of Automatic Control, Lund University (Internet http://www.control.lth.se).

### Responsible academic staff

Lectures will be held by Rolf Johansson (Rolf.Johansson@control.lth.se, phone 046-222 8791). Tutorials will be held by Meike Stemmann (Meike.Stemmann@control.lth.se, phone 046-222 9745) and Andreas Stolt (Andreas.Stolt@control.lth.se, phone 046-222 9745). Laboratory sessions will be held by Marzia Cescon, (phone 046-222 8784, Marzia.Cescon@control.lth.se) and Maria Henningsson (Maria.Henningsson@control.lth.se, phone 046-222 3270).

Office hours are Monday 4-5pm (RJ), Wednesdays 1-2pm (MS), Fridays 10.30am-12 (AS).

#### Prior knowledge required

Control Theory (FRT 010), (Mathematical Statistics—Stochastic Processes (FMS 045)).

## Reading list

• R. Johansson, System Modeling and Identification, Englewood Cliffs, NJ: Prentice Hall, 1993. ISBN 0-13-482308-7 (hard cover) or ISBN 0-13-145889-2 (paperback) (The book is currently out of stock but a 2nd edition draft is available at KFS).

Other course material such as *Laboratory Exercises* and *System Modeling and Identification—*Solutions Manual are available via our home page http://www.control.lth.se/course/FRT041/.

#### Lectures

Lectures will be held in M:E on Tuesdays 8.15-10a.m. and Thursdays at 8.15-10a.m. the Seminar Room, Dept. Automatic Control, on Wednesday, Jan 19, at 10.15-12am; on Wednesdays, Feb 2, Feb 9 at 1.15-3p.m.; M:M1 on Wednesday, Jan 26 at 1.15-3p.m. according to the following schedule:

| Week & Date |     | $\mathbf{N}^o$ | Contents |                                                                   |
|-------------|-----|----------------|----------|-------------------------------------------------------------------|
| 3           | Jan | 18             | L1:      | Introduction. Transient response analysis (RJ Chap. 1-2);         |
|             | Jan | 19             | L2:      | Frequency response analysis (RJ Chap. 2);                         |
| 4           | Jan | 25             | L3:      | Spectrum analysis (RJ Chap. 3-4). Interactive software;           |
|             | Jan | 26             | L4:      | Linear regression. Least-squares method. (RJ Chap. 5);            |
|             | Jan | 27             | L5:      | Model parametrizations (RJ Chap. 6);                              |
| 5           | Feb | 1              | L6:      | Maximum-likelihood methods (RJ Chap. 6);                          |
|             | Feb | 2              | L7:      | Prediction error methods. Algorithms. (RJ Chap. 6);               |
|             | Feb | 3              | L8:      | Modeling (RJ Chap. 7);                                            |
| 6           | Feb | 8              | L9:      | The experimental procedure (RJ Chap. 8);                          |
|             | Feb | 9              | L10:     | Model validation (RJ Chap. 9);                                    |
|             | Feb | 10             | L11:     | Model approximation (RJ Chap. 10);                                |
| 7           | Feb | 15             | L12:     | State-space models. Subspace model identification. (RJ Chap. 13); |
|             | Feb | 17             | L13:     | Real-time identification. Continuous-time models. (RJ Chap. 12);  |
| 9           | Mar | 3              | L14:     | Nonlinear system identification and 2D methods (RJ Chap. 14-15).  |

#### **Tutorials**

Tutorials will be held on Fridays 13.15-1500 (1.15pm-3pm) in MX2a. Exercises denoted 'x' are found on our web server.

| Week | Date   | Contents                          | Class             | Home work        |
|------|--------|-----------------------------------|-------------------|------------------|
| 3    | Jan 21 | E1: Frequency response analysis   | 2.3, 2.4, 8.2,8.3 | x1, 2.5, 8.4, x2 |
| 4    | Jan 28 | E2: Spectral Analysis             | 2.6, 8.5, 8.6, x3 | x4               |
| 5    | Feb 4  | E3: Linear regression             | 5.12,6.3,5.11     | x5               |
| 6    | Feb 11 | E4: Time-Series Analysis          | 8.7, x6, x7       | 6.1, 6.10, x8    |
| 7    | Feb 18 | E5: Model validation              | x9, x10,          |                  |
|      |        | Model reduction                   | 10.1, x11         | 10.2, x12        |
| 8    | Feb 25 | E6: Real-time identification      | x15, x16, x13     |                  |
|      |        | Continuous-time models            | 12.1              | 11.1             |
| 9    | Mar 4  | E7: Subspace-based identification | x18               |                  |

Information and course material is also available on www.control.lth.se

#### **Homework Assignments**

Homework assignments with mandatory hand-in of solutions will be requested during weeks 4, 6 and 7 with deadlines on January 29, February 12 and February 19.

### **Laboratory Exercises**

Laboratory exercises will be held in the course laboratory in the ground floor of the M-building. Booking for the laboratory sessions are to be found via the home page and bookings are accepted two weeks before the first session will be held. Laboratory sessions will be made in groups of three students.

| Lab     | Time  | Place | Responsible       | Phone       | Contents                    |
|---------|-------|-------|-------------------|-------------|-----------------------------|
| Lab PI1 | w.4   | Lab A | Meike Stemmann    | $222\ 9745$ | Frequency response analysis |
| Lab PI2 | w.5-6 | Lab A | Marzia Cescon     | $222\ 8784$ | Interactive identification  |
| Lab PI3 | w.8   | Lab A | Maria Henningsson | $222\ 3270$ | Synthesis                   |

## **Projects**

Projects should be made in teams of three students and the subject of study should be chosen in cooperation with the instructor by **February 12**. The project should be finished and reported during the Spring semester 2011. Oral reports will take place on **Tuesday, April 29, 10.15 a.m.**— or at a time to be decided later. The project laboratory, with computers is available to the students. An entrance card to the laboratory and permissions will be issued at **Friday, January 21 at 10.30-11.30 a.m.**, at the office of Mr. Rolf Braun, Level 2, southern wing, M-building. (Notice that a separate permission is required to enter the M-building. This should be acquired before visiting Mr. Braun.)

## **Exam and Exam Policy**

The final exam is to be given on **Monday, March 7 at 14.00-19.00 (2pm-7pm** in M:Q. Course literature (excluding old exams, exercises, and solutions) may be used during the exam. The grade of the exam (3, 4, or 5) will be posted on the notice board at the ground floor of the M-building. The final grade will be issued when the course project has been accepted. A well performed course project may increase the final grade by one unit as compared to the written exam.

# **Projects in System Identification 2011**

### A Few Suggested Project Outlines

- Identification of a flexible servo
- Identification of a helicopter model
- Identification and modeling of the ball-and-beam process—The position loop
- Parametric robot identification
- Motor drive with speed and tension control
- A servo with backlash
- Econometric identification
- Friction models for servo mechanisms
- Inverted-pendulum dynamics
- A fan process

#### **Procedure**

- Modeling
- Experiment planning
- Identification: At least two "independent" methods should be used.
- Validation:
  - Statistic criteria
  - Simulation
  - Control (if relevant)
  - Legible, nice, type-written report and a short oral presentation

### **Organisation**

- Three students in each project team
- Instructors: Rolf Johansson, Meike Stemmann, Andreas Stolt.

#### **Examination**

An oral report in class should take place on **Friday**, **April 29**, **10.15 a.m.** (or at another time to be decided). Final project reports should be submitted no later than this date.

- Examiner: Rolf Johansson
- It is required that the project is accepted to fulfill course requirements
- A well done project may improve the final grade by one unit

# Laboratory and computer resources

• Project laboratories A with computers are available with the following software: Matlab.