

$$6.3.1. \quad y(t) - 1.5y(t-1) + 0.5y(t-2) = 2(e(t) - 1.2e(t-1) + 0.6e(t-2))$$

$$y(t) = 2 \frac{1 - 1.2q^{-1} + 0.6q^{-2}}{1 - 1.5q^{-1} + 0.5q^{-2}} e(t) = \lambda \frac{C^*}{A^*} e(t)$$

$$\hat{y}(t+k|t) = \frac{G^*}{C^*} y(t)$$

$$C^* = A^* F^* + q^{-k} G^*$$

$$1 - 1.2q^{-1} + 0.6q^{-2} = (1 - 1.5q^{-1} + 0.5q^{-2})(1 + f_1 q^{-1} + \dots + f_{k-1} q^{-(k-1)}) + q^{-k}(g_0 + g_1 q^{-1})$$

$$k=1: \quad 1 - 1.2q^{-1} + 0.6q^{-2} = (1 - 1.5q^{-1} + 0.5q^{-2}) + q^{-1}(g_0 + g_1 q^{-1})$$

$$-1.2 = -1.5 + g_0 \Rightarrow g_0 = 0.3$$

$$0.6 = 0.5 + g_1 \Rightarrow g_1 = 0.1$$

$$\hat{y}(t+1|t) = 1.2\hat{y}(t|t-1) - 0.6\hat{y}(t-1|t-2) + 0.3y(t) + 0.1y(t-1)$$

$$k=2: \quad 1 - 1.2q^{-1} + 0.6q^{-2} = (1 - 1.5q^{-1} + 0.5q^{-2})(1 + f_1 q^{-1}) + q^{-2}(g_0 + g_1 q^{-1})$$

$$-1.2 = -1.5 + f_1 \Rightarrow f_1 = 0.3$$

$$0.6 = 0.5 - 1.5f_1 + g_0 \Rightarrow g_0 = 0.55$$

$$0 = 0.5f_1 + g_1 \Rightarrow g_1 = -0.15$$

$$\hat{y}(t+2|t) = \frac{0.55 - 0.15q^{-1}}{1 - 1.2q^{-1} + 0.6q^{-2}} y(t)$$

$$\text{Allmant.} \quad \hat{y}(t+k|t) = \frac{f_k - 0.5f_{k-1}q^{-1}}{1 - 1.2q^{-1} + 0.6q^{-2}} y(t) \quad k \geq 2$$

$$f_k = 1.5f_{k-1} - 0.5f_{k-2}$$

$$f_1 = 0.30$$

$$f_2 = 0.55$$

$$5.3.2. \quad y(t) + a y(t-1) = \lambda (e(t) + c e(t-1))$$

$$\underbrace{(1 + a q^{-1})}_{A^*} y = \lambda \underbrace{(1 + c q^{-1})}_{C^*} e$$

$$1 + c q^{-1} = (1 + a q^{-1})(1 + f_1 q^{-1} + \dots + f_{k-1} q^{-(k-1)}) + g_0$$

$$\underline{k=1}: \quad C = a + g_0 \Rightarrow g_0 = C - a$$

$$\underline{\hat{y}(t+1|t)} = \frac{C-a}{1+cq^{-1}} y(t)$$

$$\underline{k \geq 1}: \quad \begin{cases} C = a + f_1 \\ 0 = f_2 + a f_1 \\ 0 = f_3 + a f_2 \\ \vdots \\ 0 = a f_{k-1} + g_0 \end{cases} \Rightarrow \begin{cases} f_1 = C - a \\ f_2 = -a f_1 \\ \vdots \\ g_0 = -a f_{k-1} \end{cases}$$

$$\underline{\hat{y}(t+k|t)} = \frac{g_0}{1+cq^{-1}} y = \frac{-a f_{k-1}}{1+cq^{-1}} y = \frac{(-a)^{k-1} (C-a)}{1+cq^{-1}} y(t)$$

$$6.3.3. \quad y(t) = \frac{1}{1+aq^{-t}} e(t) + \nabla v(t) = \frac{e(t) + (1+aq^{-t}) \nabla v(t)}{1+aq^{-t}}$$

$$e(t) + (1+aq^{-t}) \nabla v(t) = \lambda(1+cq^{-t}) w(t)$$

$$\begin{cases} \phi_e + \nabla^2(1+aq^{-t})(1+aq^{-t})\phi_v = \lambda^2(1+cq^{-t})(1+cq^{-t})\phi_w \\ \phi_e = \phi_v = \phi_w = 1 \end{cases}$$

$$1 + \nabla^2(1+aq^{-t} + a^2q^{-2t} + a^4) = \lambda^2(1+cq^{-t} + cq^{-2t} + c^2)$$

$$\begin{cases} 1 + \nabla^2(1+a^4) = \lambda^2(1+c^2) \\ \nabla^2 a = \lambda^2 c \end{cases} \Rightarrow \underline{\underline{q \mu \quad c \quad \text{oder} \quad \lambda}}$$

$$y(t) = \frac{\lambda(1+cq^{-t})}{1+aq^{-t}} w(t)$$

$$1+cq^{-t} = (1+aq^{-t})(1+f_1q^{-t}) + q^{-2t}g_0$$

$$c = a + f_1 \Rightarrow f_1 = c - a$$

$$0 = a f_1 + g_0 \Rightarrow g_0 = -a(c - a)$$

$$\hat{y}(t+2|t) = \frac{-a(c-a)}{1+cq^{-t}} y(t)$$

$$6.3.4. \quad y(t) + 0.7y(t-1) = e(t) + 2e(t-1)$$

$$y(t) = \frac{1+2q^{-1}}{1+0.7q^{-1}} e(t)$$

$$\begin{cases} (1+2q^{-1})e(t) = \lambda(1+cq^{-1})w(t) & |c| < 1 \\ \Phi_e = \Phi_w = 1 \end{cases}$$

$$(1+2q^{-1})(1+2q) = \lambda^2(1+cq^{-1})(1+cq)$$

$$1+2q^{-1}+2q+4 = \lambda^2(1+cq^{-1}+cq+c^2)$$

$$\begin{cases} 5 = \lambda^2(1+c^2) \\ 2 = \lambda^2 c \end{cases} \Rightarrow \lambda^2 = \frac{2}{c}$$

$$5 = \frac{2}{c}(1+c^2) = \frac{2}{c} + 2c$$

$$c^2 - \frac{5}{2}c + 1 = 0 \Rightarrow c = \frac{5}{4} \pm \sqrt{\frac{25}{16} - 1} = \frac{5}{4} - \frac{3}{4} = \frac{1}{2}$$

$$\begin{cases} c = \frac{1}{2} \\ \lambda = 2 \end{cases}$$

$$y(t) = \frac{2(1+\frac{1}{2}q^{-1})}{1+0.7q^{-1}} e(t)$$

$$1+0.5q^{-1} = 1+0.7q^{-1} + q^{-1}q_0$$

$$0.5 = 0.7 + q_0 \Rightarrow q_0 = -0.2$$

$$\underline{\hat{y}(t+1|t) = -0.5\hat{y}(t|t-1) - 0.2y(t)}$$

$$\text{Var } \hat{y}(t+1|t) = \lambda^2 = \underline{\underline{4}}$$

$$6.3.5. \quad y(t) = \sum_{k=t_0}^t g(t, k) e(k) \quad e(t) = \sum_{k=t_0}^t h(t, k) y(k)$$

$$\begin{aligned} y(t+k) &= \sum_{l=t_0}^{t+k} g(t+k, l) e(l) = \sum_{l=t_0}^t g(t+k, l) e(l) + \sum_{l=t+1}^{t+k} g(t+k, l) e(l) \\ &= \sum_{l=t_0}^t g(t+k, l) \sum_{n=t_0}^l h(l, n) y(n) + \sum_{l=t+1}^{t+k} g(t+k, l) e(l) = \\ &= \underbrace{\sum_{l=t_0}^t \sum_{n=t_0}^l g(t+k, l) h(l, n) y(n)}_{\hat{y}(t+k|t)} + \sum_{l=t+1}^{t+k} g(t+k, l) e(l) \end{aligned}$$

$$6.3.6. \quad y(t) = \lambda \frac{C^*}{A^*} e(t)$$

$$\begin{cases} A(z) = a_0 z^n + a_1 z^{n-1} + \dots + a_n \\ C(z) = c_0 z^m + c_1 z^{m-1} + \dots + c_m \end{cases}$$

$$\hat{y}(t+k|t) = \frac{G^*}{C^*} y$$

G^* has ordn. $n-1$

C^* has ordn. m

\Rightarrow Systemet has ordningen $\text{Max}(m, n-1)$

$$6.3.7. (1 - 2.6q^{-1} + 2.85q^{-2} - 1.4q^{-3} + 0.25q^{-4})Y(t) = (1 - 0.7q^{-1})e(t)$$

$$1 - 0.7q^{-1} = 1 - 2.6q^{-1} + 2.85q^{-2} - 1.4q^{-3} + 0.25q^{-4} + q^{-1}(g_0 + g_1q^{-1} + g_2q^{-2} + g_3q^{-3})$$

$$\begin{cases} -0.7 = -2.6 + g_0 \\ 0 = 2.85 + g_1 \\ 0 = -1.4 + g_2 \\ 0 = 0.25 + g_3 \end{cases} \Rightarrow \begin{cases} g_0 = 1.9 \\ g_1 = -2.85 \\ g_2 = 1.4 \\ g_3 = -0.25 \end{cases}$$

$$\hat{Y}(t+1|t) = \frac{1.9 - 2.85q^{-1} + 1.4q^{-2} - 0.25q^{-3}}{1 - 0.7q^{-1}}$$

Dynamiken i prediktor är av tredje ordningen.

$$6.4.1. \quad y(t) = \frac{1}{1+0.5z^{-1}} u(t-1) + \frac{1+0.2z^{-1}}{1-0.2z^{-1}}$$

$$(1+0.3z^{-1}-0.1z^{-2})y(t) = (1-0.2z^{-1})u(t-1) + (1+1.2z^{-1}+0.35z^{-2})$$

$$\begin{cases} A^*(z^{-1}) = 1 + 0.3z^{-1} - 0.1z^{-2} \\ B^*(z^{-1}) = 1 - 0.2z^{-1} \\ C^*(z^{-1}) = 1 + 1.2z^{-1} + 0.35z^{-2} \end{cases}$$

$$(1+1.2z^{-1}+0.35z^{-2}) = (1+0.3z^{-1}-0.1z^{-2}) + z^{-1}(g_0 + g_1z^{-1})$$

$$1.2 = 0.3 + g_0 \quad \Rightarrow g_0 = 0.9$$

$$0.35 = -0.1 + g_1 \quad \Rightarrow g_1 = 0.45$$

$$\underline{u(t)} = -\frac{G^*}{B^*F^*} y(t) = -\frac{0.9+0.45z^{-1}}{1-0.2z^{-1}} y(t)$$

Anm. C skall ha rötter innanför enhetscirkeln.

$$z^2 + 1.2z + 0.35 = 0$$

$$z = -0.6 \pm \sqrt{0.36 - 0.35} = -0.6 \pm 0.1 \quad \text{O.K.}$$

$$6.4.2. \quad y(t) + ay(t-1) = bu(t-k) + \lambda(e(t) + ce(t-1))$$

$$(1 + aq^{-1})y(t) = bu(t-k) + \lambda(1 + cq^{-1})e(t)$$

$$\underline{k=1}: 1 + cq^{-1} = 1 + aq^{-1} + q^{-1}g_0$$

$$g_0 = c - a$$

$$\underline{u(t)} = -\frac{g_0}{b} = \underline{\frac{a-c}{b} y(t)}$$

$$\underline{\text{Var}(y)} = \lambda^2$$

$$\underline{k=2}: 1 + cq^{-1} = (1 + aq^{-1})(1 + f_1q^{-1}) + q^{-2}g_0$$

$$c = a + f_1 \Rightarrow f_1 = c - a$$

$$0 = af_1 + g_0 \Rightarrow g_0 = a(a - c)$$

$$\underline{u(t)} = -\frac{g_0}{bf^2} = \underline{\frac{a(c-a)}{b(1+(c-a)q^{-1})} y(t)}$$

$$\underline{\text{Var}(y)} = \lambda^2(1 + (c-a)^2)$$

$$\underline{k=3}: 1 + cq^{-1} = (1 + aq^{-1})(1 + f_1q^{-1} + f_2q^{-2}) + q^{-3}g_0$$

$$c = a + f_1 \Rightarrow f_1 = c - a$$

$$0 = af_1 + f_2 \Rightarrow f_2 = a(a - c)$$

$$0 = af_2 + g_0 \Rightarrow g_0 = a^2(c - a)$$

$$\underline{u(t)} = -\frac{g_0}{bf^3} = \underline{\frac{a^2(a-c)}{b(1+(c-a)q^{-1} + a^2(c-a)q^{-2})} y(t)}$$

$$\underline{\text{Var}(y)} = \lambda^2(1 + (c-a)^2 + a^2(a-c)^2)$$

$$6.4.3. \quad A^* y(t) = B^* u(t-k) \quad \underline{t > k}$$

$$u(t) = - \frac{G^*}{B^* F^*} y(t)$$

$$1 = A^* F^* + q^{-k} G^*$$

$$A^* y(t) = B^* q^{-k} u(t) = - \frac{q^{-k} B^* G^*}{B^* F^*} y(t) = - \frac{1 - A^* F^*}{F^*} y(t)$$

$$y(t) = 0$$

$\Rightarrow y(t) = 0$ after k steps \neq

$$6.4.4. \quad A^* y(t) = B^* u(t-k) + \lambda C^* e(t)$$

$$u(t) = - \frac{G^*}{B^* F^*} y(t)$$

$$1 = A^* F^* + q^{-k} G^*$$

$$A^* y(t) = - \frac{q^{-k} B^* G^*}{B^* F^*} y(t) + \lambda C^* e(t) = \frac{A^* F^* - 1}{F^*} y(t) + \lambda C^* e(t)$$

$$A^* F^* y(t) - A^* F^* y(t) + y(t) = \lambda C^* F^* e(t)$$

$$y(t) = \lambda C^* F^* e(t)$$

$$\underline{E y^k(t) = \lambda^2 (1 + (G_1 + F_1)^k + (G_2 + F_2 + G_1 F_1)^k + \dots)}$$

$$6.4.7. \quad y(t) + 0.5 y(t-1) = u(t-1) + e(t) + 2e(t-1)$$

$$(1 + 0.5q^{-1})y(t) = u(t-1) + (1 + 2q^{-1})e(t)$$

C^* har nollställe utanför enhetscirkeln.

$$\begin{cases} (1 + 2q^{-1})e(t) = \lambda(1 + cq^{-1})w(t) \\ \phi_e = \phi_w = 1 \end{cases}$$

$$(1 + 2q^{-1})(1 + 2q) = \lambda^2(1 + cq^{-1})(1 + cq)$$

$$\begin{cases} \lambda^2(1 + c^2) = 5 \\ \lambda^2 c = 2 \\ |c| < 1 \end{cases} \Rightarrow \begin{cases} \lambda = 2 \\ c = \frac{1}{2} \end{cases}$$

$$(1 + 0.5q^{-1})y(t) = u(t-1) + 2(1 + 0.5q^{-1})w(t)$$

$$1 + 0.5q^{-1} = (1 + 0.5q^{-1}) + q^{-1}g_0$$

$$g_0 = 0$$

\Rightarrow minimalvariansanalysen $\hat{u}(t) = 0$

$$E y^2 = \lambda^2 \cdot 1 = \underline{4}$$

$$6.4.8. \quad y(t) = \frac{1}{1+2q^{-1}} u(t-1) + \frac{1+0.7q^{-1}}{1-0.2q^{-1}} e(t)$$

$$\underbrace{(1+1.8q^{-1}-0.4q^{-2})}_{A^*} y(t) = \underbrace{(1-0.2q^{-1})}_{B^*} u(t-1) + \underbrace{(1+2.7q^{-1}+1.4q^{-2})}_{C^*} e(t)$$

C'rotter innanför entekskickeln?: $z^2 + 2.7z + 1.4 = 0$

$$z = -1.35 \pm \sqrt{1.35^2 - 1.4} \quad \underline{\text{nej!}}$$

$$(1+0.7q^{-1})(1+2q^{-1})e(t) = \lambda(1+0.7q^{-1})(1+Cq^{-1})w(t)$$

$$\text{Enl. 6.4.7: } \begin{cases} \lambda = 2 \\ C = 0.5 \end{cases}$$

$$C^* = (1+0.7q^{-1})(1+0.5q^{-1}) = 1 + 1.2q^{-1} + 0.35q^{-2}$$

$$C^* = A^* F^* + q^{-k} G^*$$

$$1 + 1.2q^{-1} + 0.35q^{-2} = (1 + 1.8q^{-1} - 0.4q^{-2}) + q^{-1}(g_0 + g_1 q^{-1})$$

$$1.2 = 1.8 + g_0 \quad \Rightarrow g_0 = -0.6$$

$$0.35 = -0.4 + g_1 \quad \Rightarrow g_1 = 0.75$$

$$\underline{u(t)} = \underline{-\frac{G^*}{B^* F^*} y(t)} = \underline{\frac{0.6 - 0.75q^{-1}}{1 - 0.2q^{-1}} y(t)}$$

$$E y^L = \lambda^2 \cdot 1 = \underline{4}$$

$$6.4.9. \quad u(t) = u(t-1) + K \left[\left(1 + \frac{h}{T}\right) y(t) - y(t-1) \right]$$

$$u(t) = \frac{K \left(1 + \frac{h}{T}\right) - Kq^{-1}}{1 + q^{-1}} y(t) = - \frac{G^*}{B^* F^*} y(t) = - \frac{G^*}{B^*} y(t)$$

$$\textcircled{I} \quad B^* = 1 + q^{-1} \Rightarrow F^* = 1 \Rightarrow k = 1$$

$$C^* = A^* F^* + q^{-1} G^*$$

$$(1 + c_1 q^{-1} + c_2 q^{-2}) = (1 + a_1 q^{-1} + a_2 q^{-2}) + q^{-1} (-K \left(1 + \frac{h}{T}\right) + K q^{-1})$$

Gen c_1, c_2, a_1 och a_2 .

$$A^* y(t) = B^* u(t-1) + \lambda C^* e(t)$$

$$\textcircled{II} \quad B^* = 1 \Rightarrow F^* = 1 + q^{-1} \Rightarrow k = 2$$

$$C^* = A^* F^* + q^{-2} G^*$$

$$(1 + c_1 q^{-1} + c_2 q^{-2}) = (1 + a_1 q^{-1} + a_2 q^{-2}) (1 + q^{-1}) + q^{-2} (-K \left(1 + \frac{h}{T}\right) + K q^{-1})$$

Gen c_1, c_2, a_1 och a_2 .

$$A^* y(t) = B^* u(t-1) + \lambda C^* e(t)$$

$$6.4.12. \quad A^* y(t) = B^* u(t-k) + \lambda C^* e(t)$$

$$y(t) = \frac{B^*}{A^*} u(t-k) + \lambda \frac{C^*}{A^*} e(t)$$

$$C^* = A^* F_1^* + q^{-(k+1)} G_1^* \quad F_1^* \text{ har grad } k$$

$$G_1^* \text{ har grad } n-1$$

$$y(t) = \frac{B^*}{A^*} u(t-k) + \lambda F_1^* e(t) + \lambda q^{-(k+1)} \frac{G_1^*}{A^*} e(t)$$

$$\begin{cases} y(t+k) = \frac{B^*}{A^*} u(t) + \lambda F_1^* e(t+k) + \lambda q^{-1} \frac{G_1^*}{A^*} e(t) \\ \lambda e(t) = \frac{A^*}{C^*} y(t) - \frac{B^*}{e^*} q^{-k} u(t) \end{cases}$$

$$y(t+k) = \frac{B^*}{A^*} u(t) + \lambda F_1^* e(t+k) + q^{-1} \frac{G_1^*}{C^*} y(t) - q^{-(k+1)} \frac{B^* G_1^*}{A^* C^*} u(t) =$$

$$= \lambda F_1^* e(t+k) + q^{-1} \frac{G_1^*}{C^*} y(t) + \frac{B^* F_1^*}{C^*} u(t)$$

$$\text{Välj } u(t) = \underline{-q^{-1} \frac{G_1^*}{B^* F_1^*} y(t)}$$

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$$6.5.1. \underbrace{(1 + 0.64q^{-1} + 0.22q^{-2})}_{A^*} y(t) = \underbrace{(6.4 + 19.2q^{-1})}_{B^*} u(t-3) + \lambda \underbrace{(1 - 0.82q^{-1} + 0.21q^{-2})}_{C^*} e(t)$$

eliminativariationsreglering

$$1 - 0.82q^{-1} + 0.21q^{-2} = (1 + 0.64q^{-1} + 0.22q^{-2})(1 + f_1q^{-1} + f_2q^{-2}) + q^{-3}(g_0 + g_1q^{-1})$$

$$\begin{cases} -0.82 = 0.64 + f_1 \\ 0.21 = 0.22 + f_2 + 0.64f_1 \\ 0 = f_2 \cdot 0.64 + 0.22f_1 + g_0 \\ 0 = 0.22f_2 + g_1 \end{cases} \Rightarrow \begin{cases} f_1 = -1.46 \\ f_2 = 0.9244 \\ g_0 = -0.270416 \\ g_1 = 0.203368 \end{cases}$$

$$u(t) = - \frac{g_0 + g_1q^{-1}}{B^* F^*} = - \frac{-0.270416 + 0.203368q^{-1}}{6.4(1+3q^{-1})(1-1.46q^{-1}+0.9244q^{-2})}$$

$$\underline{\text{Var } y} = \lambda^2 (1 + 1.46^2 + 0.9244^2) \approx \underline{3.99\lambda^2}$$

B har ett nollställe utanför enhetscirkeln \Rightarrow

\Rightarrow Inte min. fas \Rightarrow Känsligt för parametervariationer.

Suboptimal reglering

$$B^* = B_1^* B_2^* = 6.4 (1 + 3q^{-1})$$

$$C^* = A^* F_1^* + q^{-k} B_2^* G_1^*$$

$$1 - 0.82q^{-1} + 0.21q^{-2} = (1 + 0.64q^{-1} + 0.22q^{-2})(1 + f_1q^{-1} + f_2q^{-2} + f_3q^{-3}) + q^{-3}(1 + 3q^{-1})(g_0 + g_1q^{-1})$$

$$\begin{cases} -0.82 = 0.64 + f_1 & \Rightarrow f_1 = -1.46 \\ 0.21 = 0.64 f_1 + 0.22 + f_2 & \Rightarrow f_2 = 0.9244 \\ 0 = 0.64 f_2 + 0.22 f_1 + f_3 + g_0 \\ 0 = 0.64 f_3 + 0.22 f_2 - g_1 + 3g_0 \\ 0 = 0.22 f_3 + 3g_1 \end{cases}$$

$$f_3 + g_0 = -0.270416$$

$$\begin{cases} 0.64 f_3 + 3g_0 + g_1 = 0.203368 \\ g_1 = -0.66 f_3 \end{cases} \Rightarrow -0.02 f_3 + 3g_0 = 0.203368$$

$$-0.02 f_3 + 3(-0.270416 - f_3) = 0.203368$$

$$f_3 = -0.33596556$$

$$g_0 = 0.06554956$$

$$g_1 = 0.22173727$$

$$u(t) = - \frac{G^{1*}}{B^* F_1^*} y(t) = - \frac{0.06555 + 0.221749^{-1}}{6.4(-1.46 + 0.92449^{-1} - 0.335979^{-1})} y(t)$$

$$\underline{\text{Val } y} = (1 + 1.46^2 + 0.9244^2 + 0.33596556^2) \lambda^2 \approx \underline{4.09 \lambda^2}$$

6.5.2. 5.11 gu $y_1(z) = \lambda [c(z) + f_1 e(z-1) + \dots + f_{k-1} e(z-k+1) + f_k' e(z-k) + \dots + f_{k+n_2-1}' e(z-k-n_2+1)]$

dau $C^* = A^* F^* + q^{-k} B_2^* G'^*$

3.25 gu $y_2(z+k+n_2-1) = \lambda [e(z+k+n_2-1) + f_1 e(z+k+n_2-2) + \dots + f_{k+n_2-2} e(z-1)]$

dau $C^* = A^* F^* + q^{-k-n_2+1} G'^*$

Var $y_1(z) = \lambda^2 [1 + f_1^2 + f_2^2 + \dots + f_{k+n_2-1}^2]$

Var $y_2(z) = \lambda^2 [1 + f_1^2 + f_2^2 + \dots + f_{k+n_2-2}^2]$

6.5.3. $H(q) C(q) = A(q) F'(q) + B_2(q) G'(q)$

$A y(t) = B u(t-k) + \lambda C e(t)$

$u(t) = -\frac{q^k G'}{B, F'} y(t)$

$A y(t) = -\frac{B G'}{B, F'} y(t) + \lambda C e(t)$

$[A + \frac{B G'}{B, F'}] y(t) = \lambda C e(t)$

$[A + \frac{B_2 G'}{F'}] y(t) = \lambda C e(t)$

$[A F' + B_2 G'] y(t) = \lambda C F' e(t)$

$H y(t) = \lambda F' e(t)$

$$\left[A + \frac{B G'}{B, F'} \right] y(t) = \lambda C e(t)$$

$$[A B, F_1 + B_2 G'] y(t) = \lambda C B, F' e(t)$$

$$B, [A F_1 + B_2 G'] y(t) = \lambda C B, F' e(t)$$

$$B, H C y(t) = \lambda C B, F' e(t)$$

⇒ Karakteristiska polynomet = $B, H C$ ≠

S.S.4. $A^* y(t) = B^* u(t-k) + \lambda C^* e(t)$

$$u(t) = - \frac{G_1^*}{F_1^*} y(t)$$

$$C^* = A^* F_1^* + q^{-k} B^* G_1^*$$

$$A^* y(t) = - \frac{q^{-k} B^* G_1^*}{F_1^*} y(t) + \lambda C^* e(t)$$

$$[A^* F_1^* + q^{-k} B^* G_1^*] y(t) = \lambda C^* e(t)$$

$$C^* y(t) = \lambda C^* e(t)$$

$$q^{n+k-1} C = A F_1 + B G_1$$

$$q^{n+k-1} C y(t) = \lambda q^{n+k-1} e(t)$$

⇒ Kar. pol = $q^{n+k-1} C$

$$\underline{\text{Var } y = \lambda^2 (1 + f_1'' + \dots + f_{k+n-1}'')}$$

$$\underline{\text{ellin var } y = \lambda^2 (1 + f_1' + \dots + f_{k-1}')}$$

$$6.5.5. \quad (1+aq^{-1})y(t) = (1+2.5q^{-1}+q^{-2})u(t-1) + (1+cq^{-1})e(t)$$

Minimalvariansstrategi

$$1+cq^{-1} = (1+aq^{-1}) + q^{-1}g_0$$

$$c = a + g_0 \Rightarrow g_0 = c - a$$

$$u(t) = \frac{a-c}{(1+2.5q^{-1}+q^{-2})} y(t)$$

reglerfelet $y(t) = e(t)$

$$z^2 + 2.5z + 1 = 0$$

$$z = -1.25 \pm \sqrt{1.25^2 - 1} = -1.25 \pm 0.75 = -2, -0.5$$

B har nollställe utanför enhetscirkeln \Rightarrow icke min. fas \Rightarrow
 \Rightarrow känsligt för parametervariationer.

Suboptimal strategi 1

$$B^* = B_1^* B_2^* = (1+0.5q^{-1})(1+2q^{-1})$$

$$C^* = AF_1^* + q^{-1}B_2^* G_1^*$$

$$1+cq^{-1} = (1+aq^{-1})(1+f_1q^{-1}) + q^{-1}(1+2q^{-1})g_0$$

$$\begin{cases} c = a + f_1 + g_0 \\ 0 = af_1 + 2g_0 \end{cases} \Rightarrow \begin{cases} f_1 = \frac{2(c-a)}{2-a} \\ g_0 = -\frac{a(c-a)}{2-a} \end{cases}$$

$$u(t) = \frac{-\frac{a(c-a)}{2-a}}{\left(1 + \frac{2(c-a)}{2-a}q^{-1}\right)(1+0.5q^{-1})} y(t)$$

reglerfelet $y(t) = e(t) + \frac{2(c-a)}{2-a} e(t-1)$

Suboptimal strategi 2

$$c^* = A^* F_1^* + q^{-1} B^* G_0^*$$

$$1 + Cq^{-1} = (1 + aq^{-1})(1 + f_1 q^{-1} + f_2 q^{-2}) + q^{-1}(1 + 2.5q^{-1} + q^{-2})g_0$$

$$\begin{cases} c = a + f_1 + g_0 \\ 0 = a f_1 + f_2 + 2.5g_0 \\ 0 = a f_2 + g_0 \end{cases} \Rightarrow \begin{cases} f_1 + g_0 = c - a \\ a f_1 - g_0/a + 2.5g_0 = 0 \\ f_2 = -g_0/a \end{cases}$$

$$a(c - a - g_0) - g_0/a + 2.5g_0 = 0$$

$$(-a - \frac{1}{a} + 2.5)g_0 = -a(c - a)$$

$$g_0 = \frac{a^2(c - a)}{a^2 - 2.5a + 1}$$

$$f_2 = \frac{-a(c - a)}{a^2 - 2.5a + 1}$$

$$f_1 = c - a - g_0 = \frac{(c - a)(a^2 - 2.5a + 1) - a^2(c - a)}{a^2 - 2.5a + 1} = \frac{(c - a)(1 - 2.5a)}{a^2 - 2.5a + 1}$$

$$u(t) = - \frac{G_1^*}{F_1^*} y(t) = - \frac{\frac{a^2(c - a)}{a^2 - 2.5a + 1}}{1 + \frac{(c - a)(1 - 2.5a)}{a^2 - 2.5a + 1} q^{-1} - \frac{a(c - a)}{a^2 - 2.5a + 1} q^{-2}} y(t)$$

$$\text{Replacet } y(t) = e(t) + \frac{(c - a)(1 - 2.5a)}{a^2 - 2.5a + 1} e(t - 1) - \frac{a(c - a)}{a^2 - 2.5a + 1} e(t - 2)$$